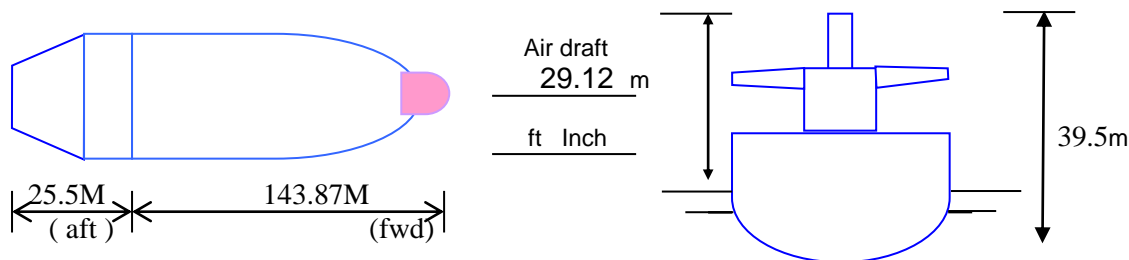


Complete with most up-to-date information and hand over to pilot by Master and make entry in bridge movement book.

Arrival Port	<b>MARSDEN POINT, NEW ZEALAND</b>		Date	<b>24 DECEMBER 2025</b>	
<b>SHIP'S PARTICULARS</b>					
Name	<b>MOUNT OWEN</b>		Call sign	<b>VRDU6</b>	IMO No. <b>9444924</b>
Deadweight	<b>29502</b>	Year built	<b>2008</b>	Length OA	<b>169.37m</b> Breadth <b>27.20m</b>
Displacement	<b>35922</b>	Bulbous Bow	<b>Yes</b>	GRT/NRT	<b>17018 / 10104</b>
Draught Fwd	<b>9.82 m</b>	Draught Amidships	<b>10.13 m</b>	Draught Aft	<b>10.38 m</b>
Freeboard	<b>3.48 m</b>				
Propeller Immersion	<b>100%</b>		Cargo /Quantity	<b>LOGS / 28520MT</b>	
Port anchor	<b>11 Shackles</b>		Stbd anchor	<b>11 Shackles</b>	

1 shackles=27.4 m/15 fathoms One fathom = 6 feet



<b>ENGINE</b>			
Type of Engine	6S42MC	EPL Implemented *	YES
Max. Continuous Power (CSR)	5850 KW / 7953 BHP	Maximum Power after EPL	OVERRIDDEN FOR MANEUVERING CONDITION
	<b>RPM</b>	<b>Loaded Speed</b>	<b>Ballast Speed</b>
Full ahead	<b>95</b>	11.5 KTS	11.9 KTS
Half Ahead	<b>80</b>	9.7 KTS	9.9 KTS
Slow ahead	<b>58</b>	7.0 KTS	7.3 KTS
Dead Slow ahead	<b>42</b>	5.1 KTS	5.3 KTS
<b>Astern power</b>		30 % of Ahead power	
Dead Slow Astern	<b>42</b>	*EPL can be overridden in 1-2 mins., when requested by Pilot.	
Slow Astern	<b>58</b>		
Half Astern	<b>80</b>		
Full Astern	<b>95</b>		
Engine Critical RPM	<b>63 - 76</b>	Maximum Number of Consecutive engine Starts	<b>12</b>
Time full ahead to full astern	<b>3 minutes</b>	Time limit astern	<b>20 minutes</b>
Rudder Type	1 / Balance Rudder type	Maximum Angle	<b>35 degrees</b>
Time from hard-over to hard-over:	2 pumps / <b>26 sec</b>	Minimum Steering Speed: <b>3 kts – 4 kts</b>	

## Equipment Checked and Ready for Use

Anchors:	Cleared away:
Compasses:	Gyro and Magnetic Compass
Compass error:	0.8° W
Speed log:	Doppler: Yes      Speed: Water      Axis: Dual
Echo Sounder	Yes
GPS:	Type: <b>DGPS</b>
ECDIS: (Assigned for pilot's use )	Make: MARIS      Location/No.: Conning-Port / Monitoring-Stbd Planning/Port beside GMDSS Equip
	ENC available and updated. ECDIS Alarm & Safety frame On. Safety Depth_10.5m, Safety Contour _10.5 m ECDIS Display Mode: "All" Display
X-Band radar:	ARPA: <b><u>Yes</u></b>
S-Band radar:	ARPA: <b><u>Yes with LCD issue</u></b>
VHF (including handheld):	<b>Yes</b>
Steering gear:	Number of power units in use: 1 and 2
Engine telegraphs:	<b>Yes</b>
Rudder / RPM indicators:	<b>Yes</b>
Mooring winches and line:	<b>Yes</b>
Navigation lights	<b>Yes</b>
Whistle	<b>Yes</b>

Equipment operational defects, ship handling and maneuvering limitations, if any:

OTHER IMPORTANT DETAILS (e.g. ship windage area, position of automatic Identification System (AIS) antenna, safe working load (SWL) of bollards), tug push markings on hull

Maneuvering Characteristics in Shallow Waters - Advance, transfer and stopping distance of the vessel will **considerably increase in shallow waters to > 2 times of the value in deep waters**, other external factors remaining constant,)

Advance: ( <b>B-465m</b> ) (L-500m)	Transfer ( <b>B-225m</b> ) / (L-255m)	Stopping Distance ( <b>F. Ahead to F. Astern</b> ) ( <b>B-1575m</b> ) / ( <b>L-2385m</b> )
Propeller	<b><u>Right handed</u></b>	Gyro Error : ° High (+) / Low (-) <b>0.8° W</b>

**Manoeuvring on ships fitted with bridge control:**

- 1) Operation may be done using Bridge control after risk assessment by Master and Chief Engineer except for JNS vessels.
- 2) C/Engineer shall ensure that the ME is tested on Bridge and ECR control both ahead and astern prior manoeuvring and then changed to Bridge or ECR control as appropriate.

<b>Duty Officer: Name / Sign</b>	<b>Master: Name / Sign</b> <b>Capt. Mojica, Eugene T.</b>	<b>Pilot : Name / Sign</b>
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